EECE5512 Networked XR Systems

Lecture Outline for Today

- 360-Degree VR Video Streaming
 - Viewport
 - Viewport prediction
 - Viewport culling
 - Viewport adaptation
- Homework3



3-DoF on angular motion

☐ Central to many immersive applications (e.g., VR/AR)



Image credit: Oculus

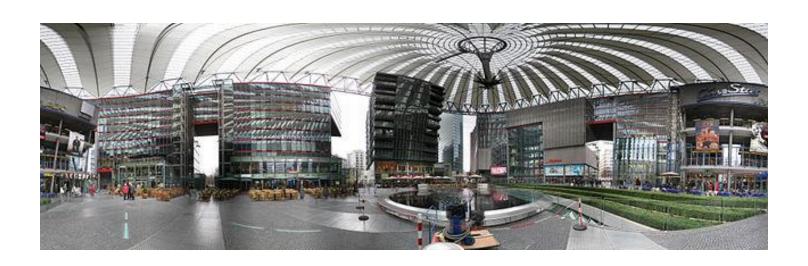
Immersive Experience



S Billion Market

- Motion-to-photon latency a unique metric of importance compared to regular videos
 - "the lag between a user making a movement and the movement being displayed within the display"
 - Should be in the order of a few 10s of milliseconds (<20ms)
- Other metrics that we discussed in case of regular videos still apply here (e.g., quality, stalls., etc.)

- How to compress 360-degree videos?
 - Often projected to a 2D equirectangular video and then adopt standard video codecs

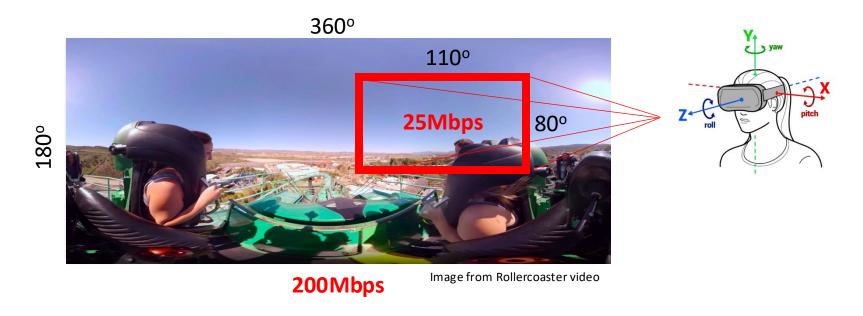


 How streaming a 360-degree video is different from regular video?

• Stream it like a regular video - problem?

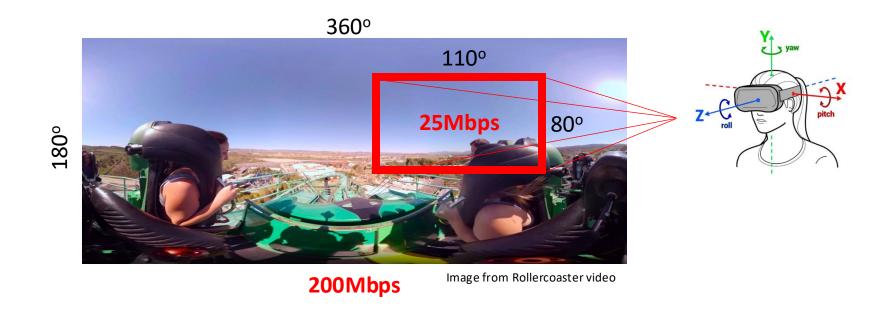
Streaming Challenge

How streaming a 360-degree video is different from regular video?



360° videos require more bandwidth compared to regular videos for the same perceived quality

Streaming Challenge



Can we just stream the viewport?

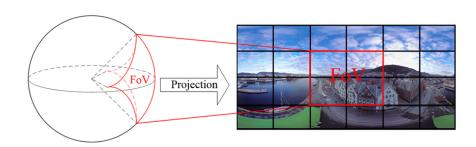
Viewport-Adaptive Streaming

- How to stream a viewport?
 - There can be many viewports i.e., different users may look different parts of the scene at different times during the video
 - Viewport is continuous stream of pixels hard to identify viewport pixels and stream viewport directly

☐ Tiled Streaming

• Divide video into tiles (e.g., 192x192 pixels)

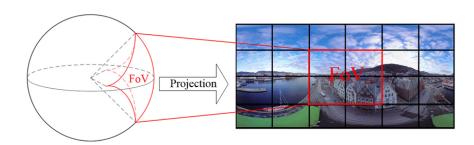




☐Tiled streaming

- Divide video into tiles (e.g., 192x192 pixels)
- Predict viewport tiles based on head tracking and video saliency analysis
- Stream only viewport specific tiles

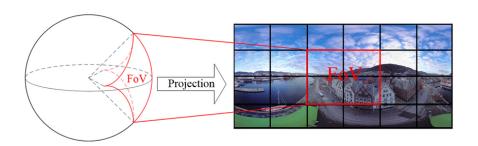




☐Tiled streaming

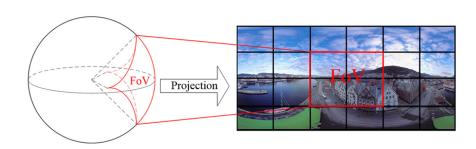
- Divide video into tiles (e.g., 192x192 pixels)
- Predict viewport tiles based on head tracking and video saliency analysis
- Stream only viewport specific tiles





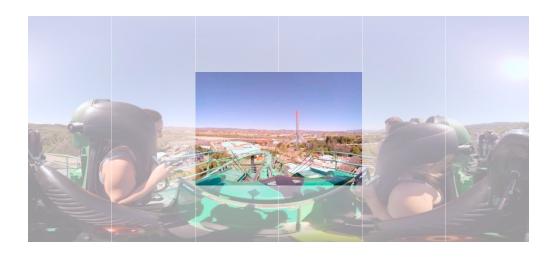
- Viewport prediction
 - Use video features and users' past history (i.e., head motion data) to predict where the user will look at in the near future
 - Need prediction models





- Viewport prediction
 - Use video features and users' past history (i.e., head motion data) to predict where the user will look at in the near future
 - Need prediction models

User head motion ->



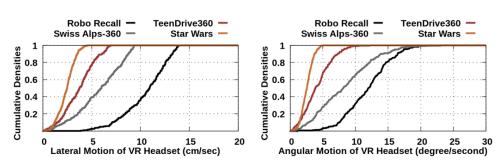


Figure 3: CDFs of VRH linear and angular speeds for VR applications.

- Viewport prediction
 - Use video features and users' past history (i.e., head motion data) to predict where the user will look at in the near future
 - Need prediction models



Which tiles and how many tiles to stream?



Saliency features ->

- Viewport prediction
 - Use video features and users' past history (i.e., head motion data) to predict where the user will look at in the near future
 - Need prediction models



Which tiles and how many tiles to stream?



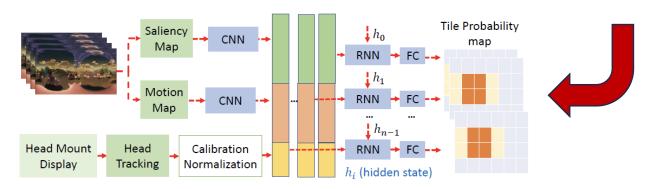
Attention features ->

- Viewport prediction models
 - Simple ML Models (e.g., SVM)
 - Faster, less accurate
 - Neural Networks
 - Slower, slightly more accurate

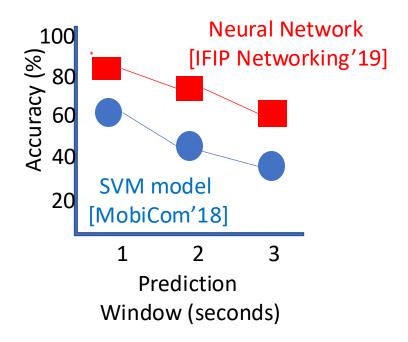


- Viewport prediction models
 - Simple ML Models (e.g., SVM)
 - Faster, less accurate
 - Neural Networks
 - Slower, slightly more accurate





- □ Viewport prediction models
 - Predicting user head movement is hard
 - The accuracy drops significantly as we predict a longer horizon user motion

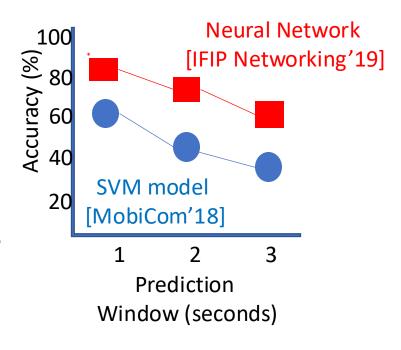


□ Viewport prediction models

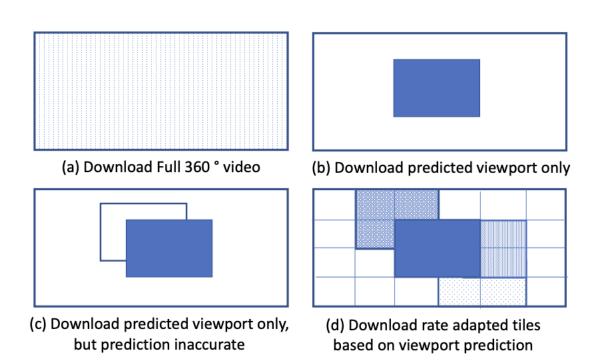
Predicting user head movement is hard

Solution:

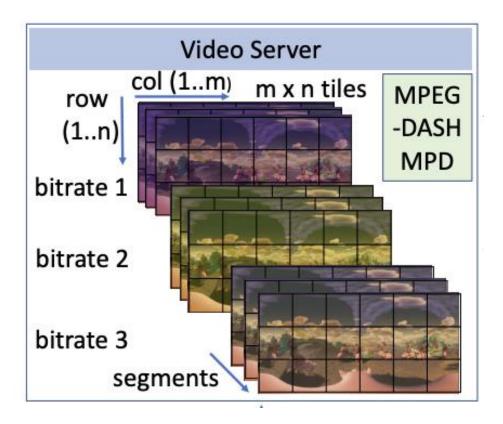
- Fetch more tiles to avoid the tile misses
- Fetching more tiles competes for bandwidth and reduces video quality



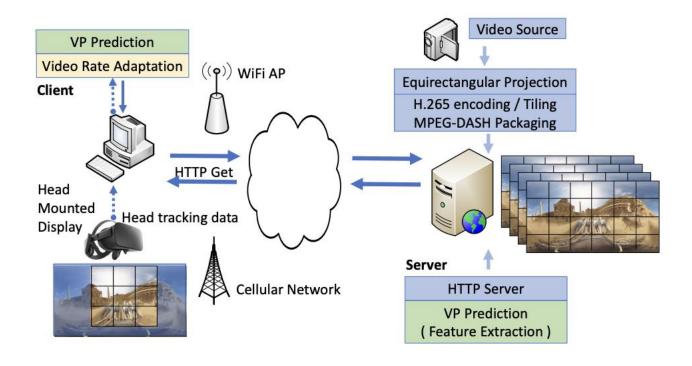
Tile selection strategies



Tiles stored at the server in different qualities



End-to-end streaming pipeline



Equation: Tile Selection Optimization

Let T be the set of all tiles in a video frame, and V_p be the set of tiles within the predicted viewport. Each tile t has an associated quality level q_t and required bitrate $b_t(q_t)$. The optimization problem aims to maximize the overall quality of the viewport under the total available bandwidth B.

Objective:

$$\max_{\{q_t\}} \sum_{t \in V_p} w(t) \cdot q_t$$

Subject to:

$$\sum_{t \in T} b_t(q_t) \leq B$$

where w(t) is the weight (importance) of tile t based on its position within the predicted viewport V_p , reflecting the user's likely focus area.

We need throughput estimation similar to the case of regular videos

Equation: Throughput Estimation

Let T_i be the throughput estimate after downloading the i-th video segment, S_i be the size of the i-th segment (in bits), and D_i be the download duration (in seconds). The throughput estimate can be updated as:

$$T_{i+1} = lpha \cdot T_i + (1-lpha) \cdot \left(rac{S_i}{D_i}
ight)$$

where $0<\alpha<1$ is a smoothing factor that controls the impact of past throughput measurements on the current estimate.

- Tile Miss Ratio
 - measures how often a user's viewport contains tiles that were not pre-fetched or delivered at the desired quality.

The Tile Miss Ratio is calculated as:

$$TMR = \frac{\sum (missed tiles in viewport)}{\sum (total tiles in viewport)}$$

Where:

- **Missed tiles** refer to tiles that are either delivered at a lower-than-desired quality or not delivered in time to be displayed when the user shifts their viewport.
- Total tiles in viewport refer to the total number of tiles that should have been displayed at high quality.

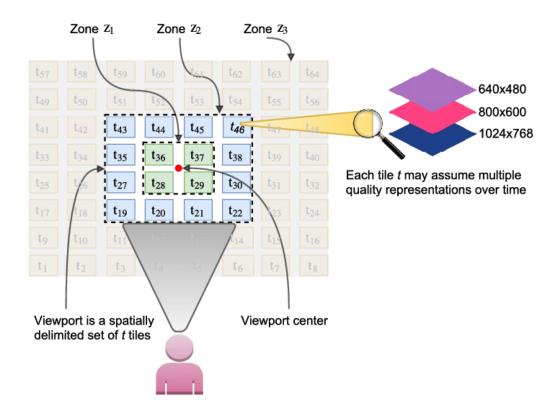
You are given a 360-degree video streaming scenario where the video sphere is divided into **100 tiles**. The system uses a **viewport-adaptive streaming** mechanism to stream only the tiles within a user's **90-degree** horizontal field of view.

Assume the following:

- A user's viewport can cover 25 tiles at a time.
- The system predicts the viewport for the next 1 second and fetches tiles accordingly.
- Due to unpredictable head movements, the user's actual viewport deviates from the prediction by 10% on average.
- The available bandwidth allows for 20 tiles per second to be streamed at high quality.
- If a tile is not delivered in high quality, it is considered a "missed tile" for that frame.

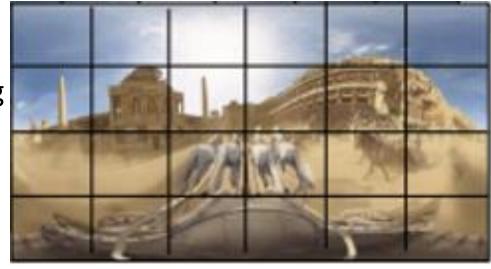
Calculate the Tile Miss Ratio based on the given data

Need to adapt spatial quality as well

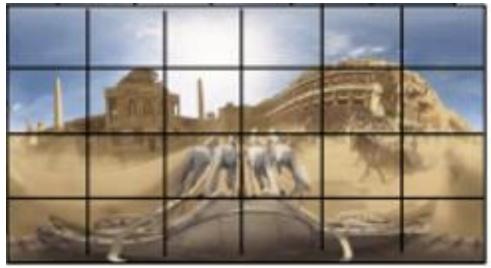


- Compression overhead with tiling
 - Looses out on exploiting spatio-temporal redundancy that existing across the tiles

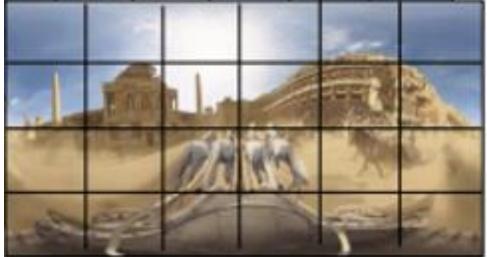
• Why?



- Compression overhead with tiling
 - Looses out on exploiting spatio-temporal redundancy that existing across the tiles
 - Why?
 - Tiles need to be encoded independently so that can be streamed independently

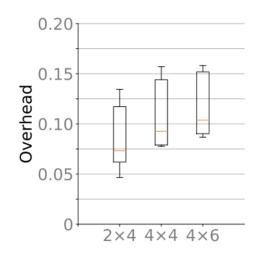


- Compression overhead with tiling
 - Looses out on exploiting spatio-temporal redundancy that existing across the tiles



• Why?

 Tiles need to be encoded independently so that can be streamed independently



Summary of the Lecture

- 360-Degree Video Streaming
 - Viewport prediction
 - Viewport adaptation