Meta Connect:

Meta Ray-Ban Displays



https://about.fb.com/news/2025/09/meta-ray-ban-display-ai-glasses-emg-wristband/

EECE5512 Networked XR Systems

Last Class - Recap

- Remaining XR/3D Data Representations
 - Implicit Neural Representations
 - Gaussian splats
- View Immersion
- Capturing 3D Videos for Network Transmission
 - Scene Capture
 - Network & Application Interplay
 - Capture Scenarios: Outside-in vs. Inside-out Capture
 - Offline vs. Live Capture
 - Depth Maps, Point Cloud, and Mesh Capture
 - Compute, Bandwidth vs. Latency Trade-offs

Lecture Outline for Today

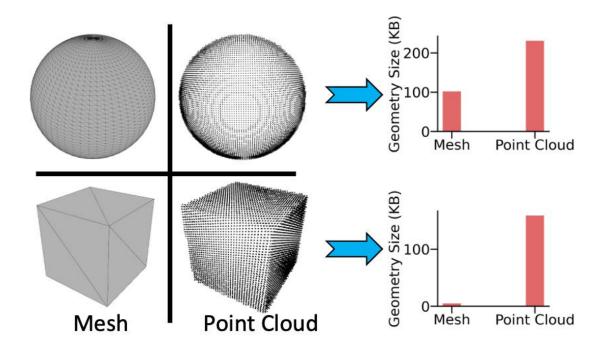
- Live 3D Capture
- Network Capacity vs. Requirements of Applications
- Compression Fundamentals
- 2D Video Compression

Live 3D Capture

- Depth Map vs. Point Cloud vs. Mesh
- Implications on the network?
 - Each data structure has significantly different bandwidth requirement
 - It is unclear which is better still in experimental research phase, no consensus yet; need to study diverse scenarios.

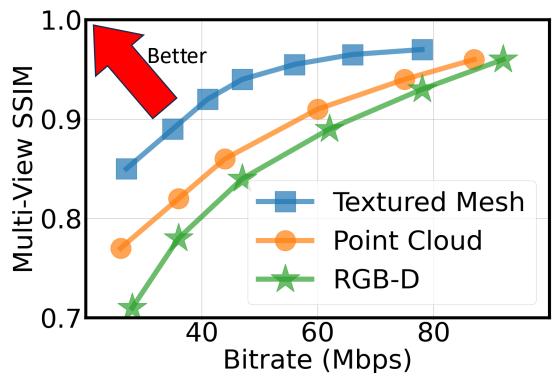
Early Findings

Mesh is compact



Early Findings

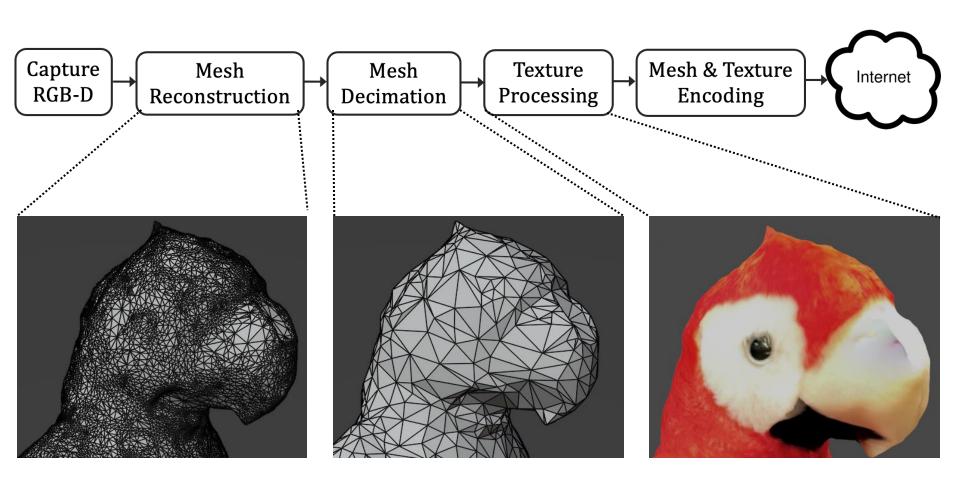
 Mesh requires relatively lower bandwidth for a given final rendering visual quality



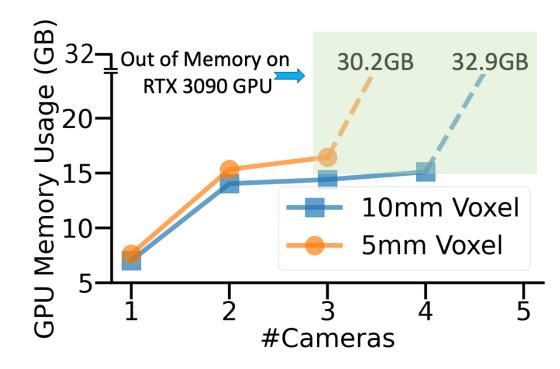
Live 3D Capture

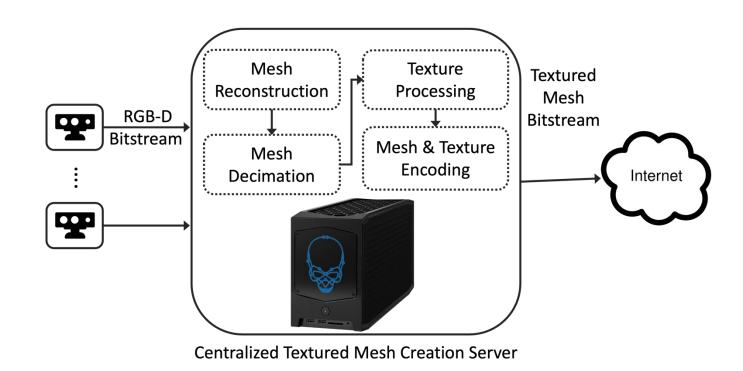
- Depth Map vs. Point Cloud vs. Mesh
- Meshes are generally superior assuming we can tackle the computation challenge on the sender side
- Several reasons
 - Compact
 - High resolution texture
 - Compatible for rendering hardware triangles

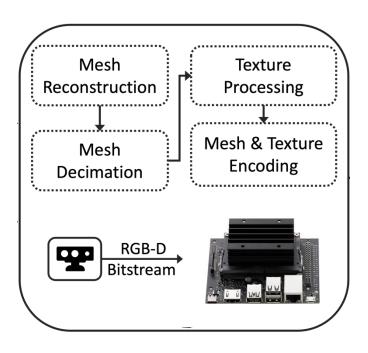
- Texture is given we can use existing hardware pipelines for 2D videos to capture and stream textures
- Extracting meshes is a complex process
 - Involves a series of computationally expensive reconstruction steps
 - Outside-in scenario: fusing multiple scenes together; adds additional computation

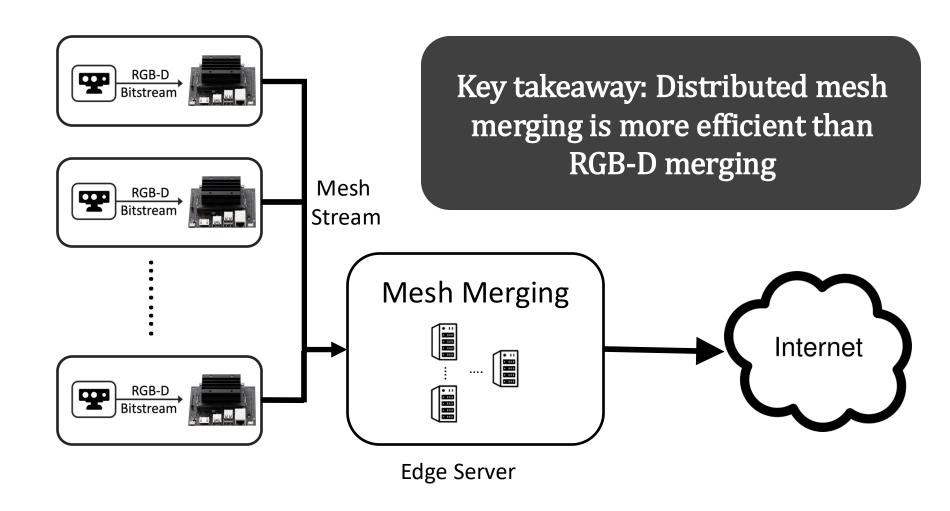


- Single camera vs. multi camera reconstruction
 - GPU runs out of memory quickly
 - Depends on the voxel resolution
 - What is voxel?

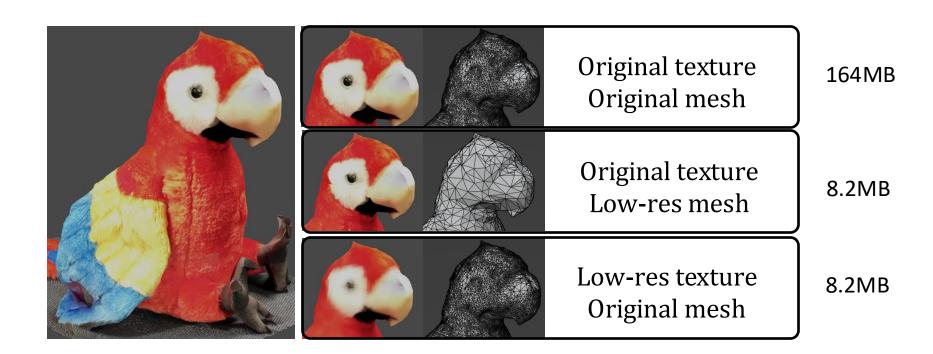








• Texture vs. Mesh bandwidth



Lecture Outline for Today

- Live 3D Capture
- Network Capacity vs. Requirements of Applications
- Compression Fundamentals
- 2D Video Compression

Today's Internet

- Wired
 - Fiber, Cable
- Wireless
 - Cellular
 - WiFi
 - Satellite

Internet speeds

- What are the max speeds for today's Internet?
 - Wired
 - Cellular
 - WiFi
 - Satellite

Internet type	Max speed	
Fiber	10,000Mbps (5 Gbps)	
Cable	1,200Mbps (1.2 Gbps)	
DSL	100Mbps	
5G	1,000Mbps (1 Gbps)	
4G LTE	9-50Mbps	
Fixed wireless	100Mbps	
Satellite	100Mbps	

What are the average speeds?

- Wired = 1 gbps
- WiFi = ~ 100Mbps
- Cellular = ~ 100Mbps

- Depends on the location
 - Campuses, Homes, Urban, Rural, Country (Developed vs. Developing worlds)
 - Many factors

How much Internet speed you need?

	Minimum	Recommended
Email	1Mbps	1Mbps
Web browsing	3Mbps	5Mbps
Social media	3Mbps	10Mbps
Streaming SD video	3Mbps	10Mbps
Streaming HD video	5Mbps	25Mbps
Streaming 4K video	25Mbps	100Mbps
Online gaming	5Mbps	100Mbps
Streaming music	1Mbps	5Mbps
One-on-one video calls	1Mbps	25Mbps
Video conference calls	2Mbps	50Mbps

2D Video as an Example

- How much bandwidth does a 2D movie needs
 - Example: 2-hour movie, 30 Fps, 8-bit depth, 1080p

- Total = 2x60x60x30x3x1920x1080 Bytes or 1.25TB or 1.4Gbps
- On a home WiFi with say average 150Mbps speed, it takes about 19 hours to download this movie

2D Video as an Example

But you're watching your Netflix movie in real-time

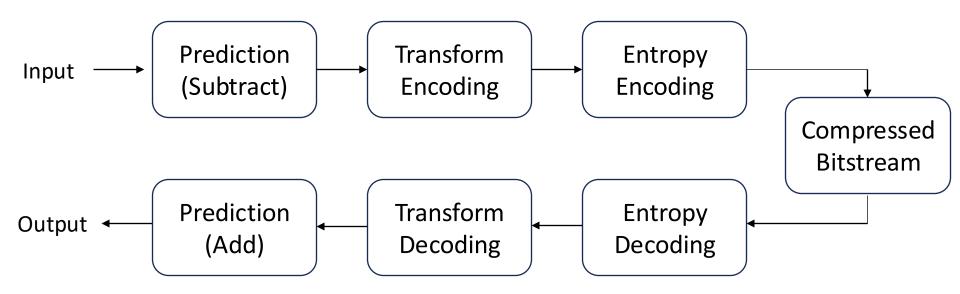


Compression Fundamentals

- Two types of compression methods
 - Lossless
 - No loss of information
 - Lossy
 - There is some information loss.. But perceptually not much
 - Useful in case of poor Internet speeds

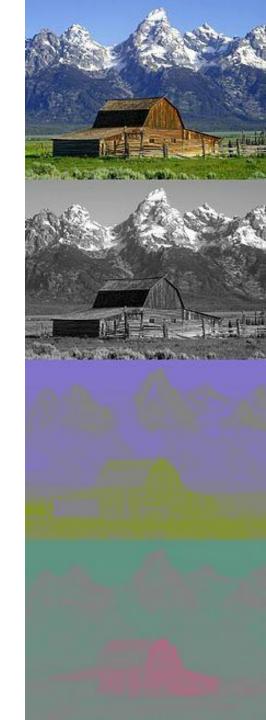
Compression Fundamentals

- Key steps involved in video compression pipeline
 - Color space or Chroma sub-sampling

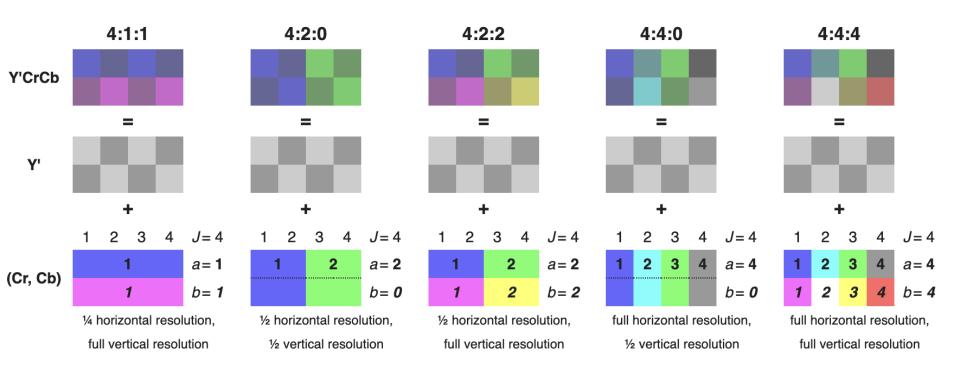


Chroma Sub-sampling

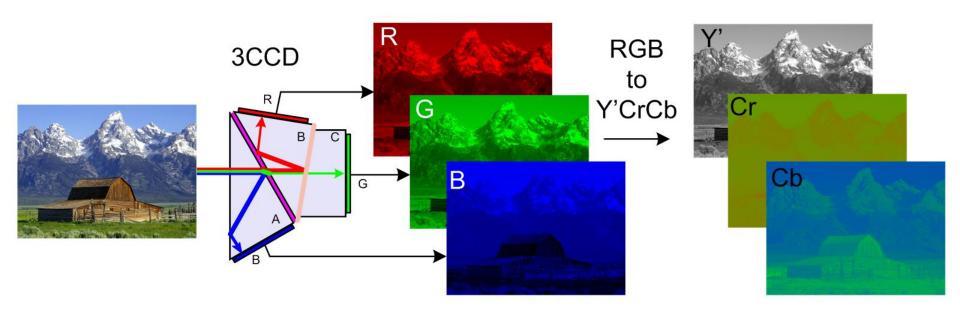
- RGB 3 channels
 - Gives equal importance to all 3 channels
- YCbCr 3 channels
 - Gives more importance to Luma
 - Less importance to Chroma
 - Perceptually minimal or no loss
- The Y image on the right is essentially a greyscale copy of the main image.



Chroma Sub-sampling



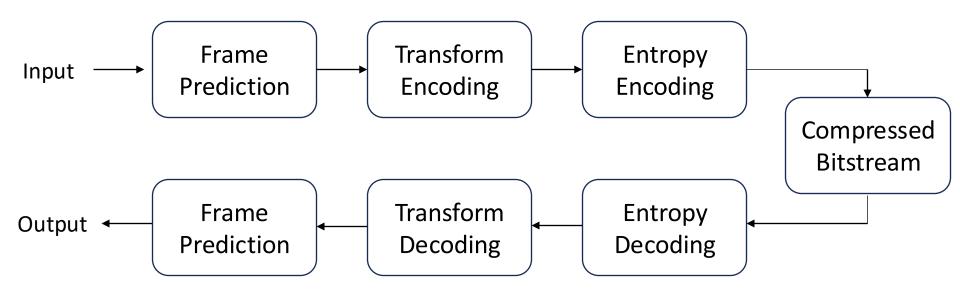
Chroma Sub-sampling



$$Y' = 16+ rac{65.738 \cdot R'_D}{256} + rac{129.057 \cdot G'_D}{256} + rac{25.064 \cdot B'_D}{256} \ C_B = 128- rac{37.945 \cdot R'_D}{256} - rac{74.494 \cdot G'_D}{256} + rac{112.439 \cdot B'_D}{256} \ C_R = 128+ rac{112.439 \cdot R'_D}{256} - rac{94.154 \cdot G'_D}{256} - rac{18.285 \cdot B'_D}{256}$$

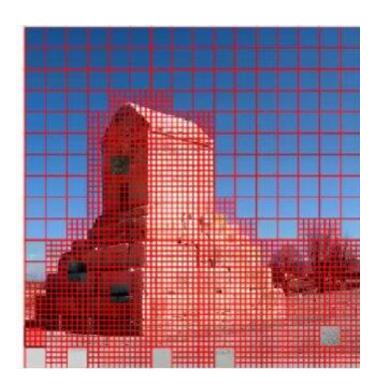
Compression Fundamentals

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- Exploiting redundancy in the video content
 - Intra frame prediction
 - Within the frame spatial redundancy
 - Inter frame prediction
 - Across the frames—temporal redundancy

Block size matters

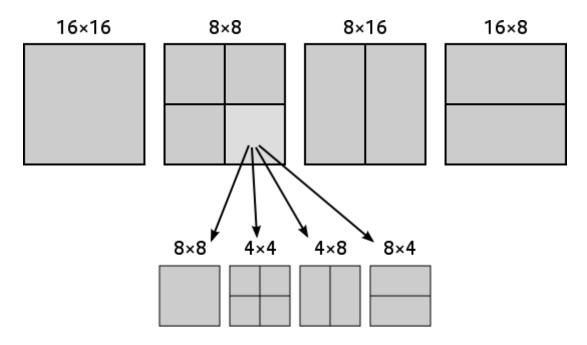


Intra prediction

Since neighboring pixels
within an image are often
very similar, rather than
storing each pixel
independently, the frame
image is divided into
blocks and typically
minor difference between
each pixel can be
encoded using fewer bits.

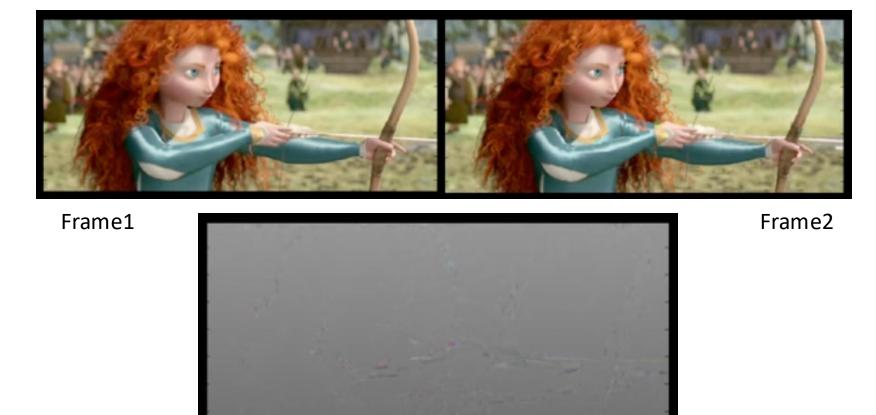
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Typical Block Sizes or Macroblock sizes



Latest compression algorithms can do up to 64x64 blocks of pixels (for 4K or 8K videos)

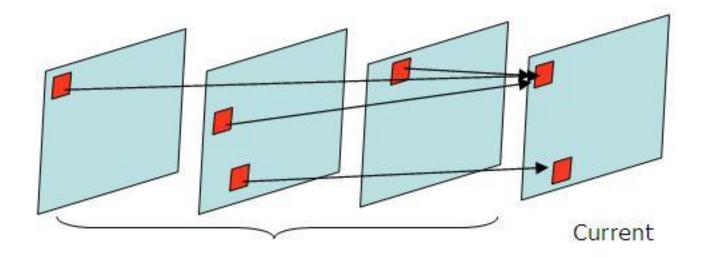
• Inter Frame Prediction



Residual – very little *information*

Source: vcodexer

- Instead of directly encoding the raw pixel values for each block, the encoder will try to find a block similar to the one it is encoding on a previously encoded frame, referred to as a reference frame.
- This process is done by a block matching algorithm.



- If the encoder succeeds on its search, the block could be encoded by a vector, known as motion vector, which points to the position of the matching block at the reference frame.
- The process of motion vector determination is called motion estimation.

Motion vector visualization

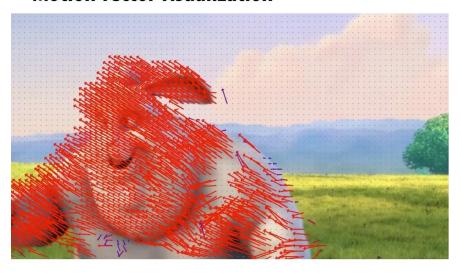
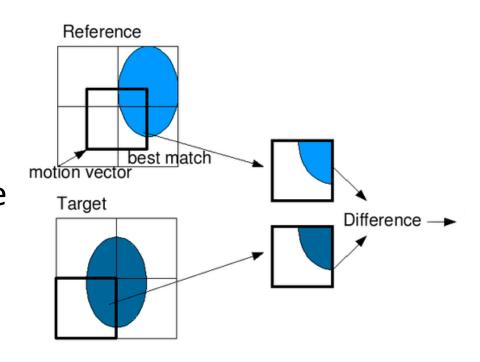


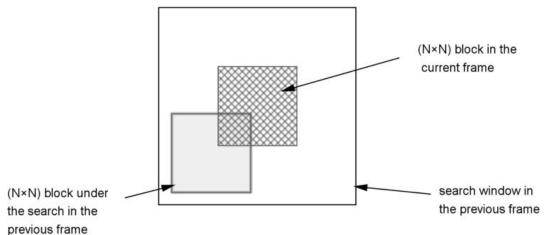
Image credit: Keyi Zhang

Stanford CS348K, Spring 202

 In most cases the encoder will succeed, but the block found is likely not an exact match to the block it is encoding. This is why the encoder will compute the differences between them. Those residual values are known as the prediction error



Block Matching Algorithm

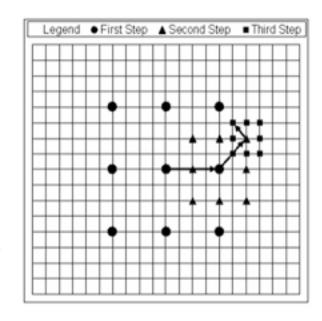


Mean difference or Mean Absolute Difference (MAD) =
$$rac{1}{N^2}\sum_{i=0}^{n-1}\sum_{j=0}^{n-1}|C_{ij}-R_{ij}|$$

Mean Squared Error (MSE) =
$$\frac{1}{N^2}\sum_{i=0}^{n-1}\sum_{j=0}^{n-1}(C_{ij}-R_{ij})^2$$

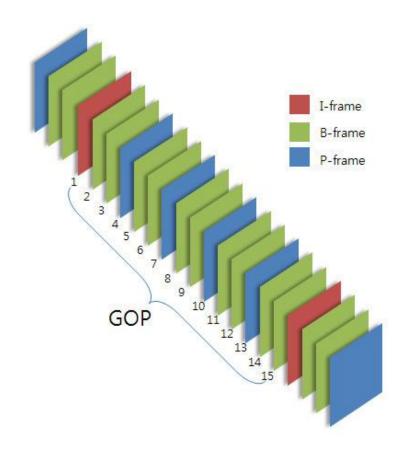
Inter Frame Prediction

- Types of Block Matching Algorithms
 - Exhaustive search
 - A 3-step search
 - Hexagon or Diamond search
 - Computationally very intensive
 - This must be done for each block of pixels for each frame referencing multiple frames



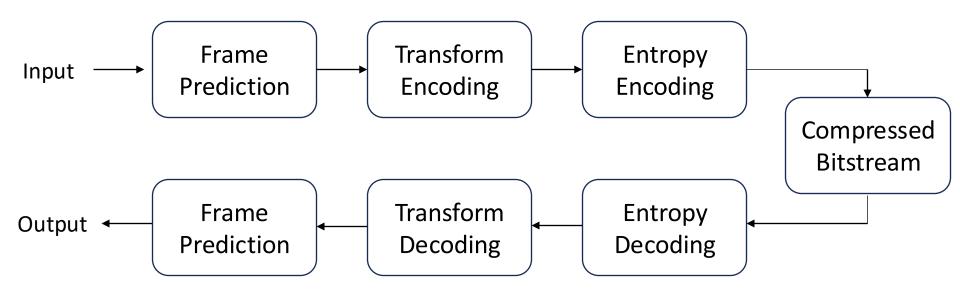
Inter Frame Prediction

- Three types of frames
 - I standalone frame, refers itself
 - P refers to past frames (I or P)
 - B refers to previous and future frames (P or B)
- Group of pictures (GOP)

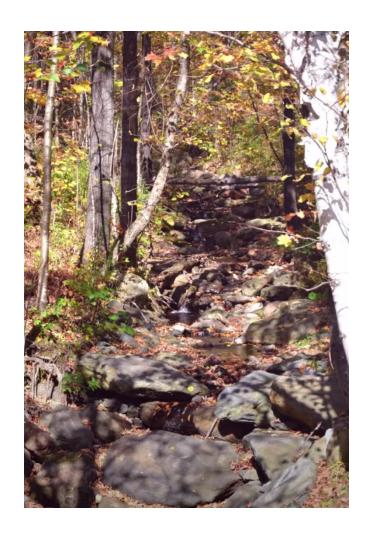


Compression Fundamentals

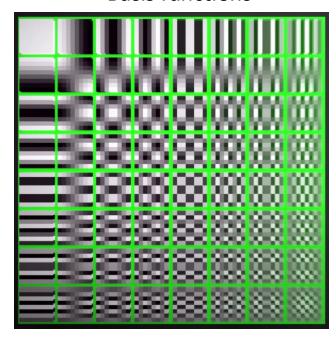
- Key steps involved in video compression pipeline
 - Color space or Chroma sub-sampling



- Transform encoding and quantization
 - Our eyes are bad at perceiving high frequency data
 - Throw away a lot of such data – negligible quality loss



Basis functions



8x8 DCT Transform

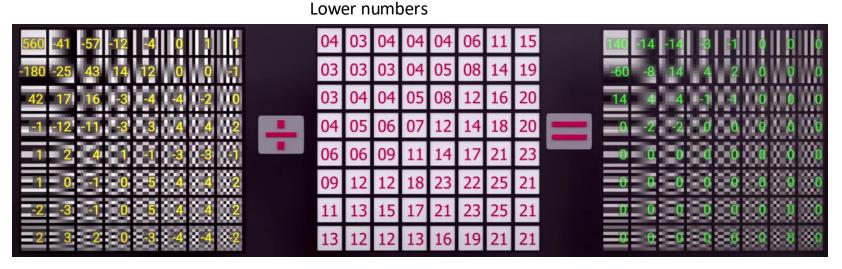
Input image



64 constants that represents how much of each base image is used

DCT Coefficients

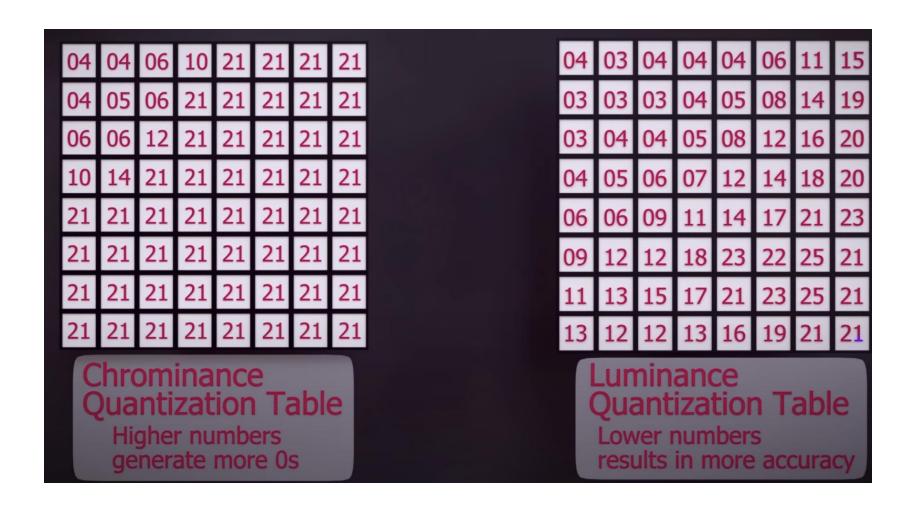
- Transform encoding and quantization
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DCT'd image

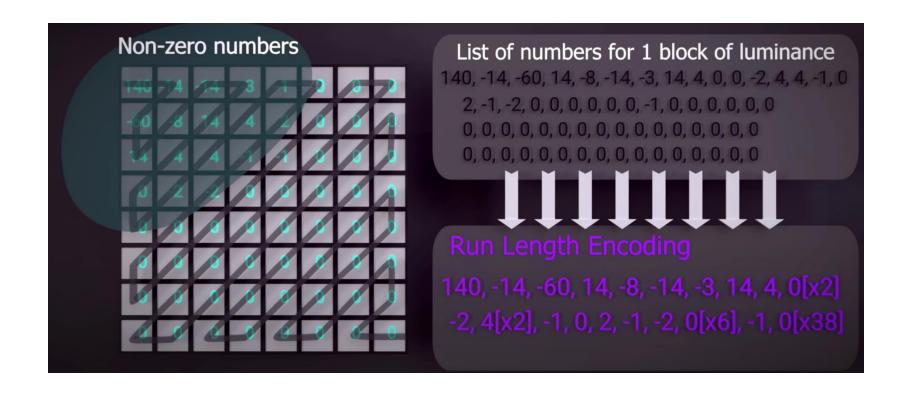
Quantization table

Compressed image



Entropy Coding

Zigzag Encoding



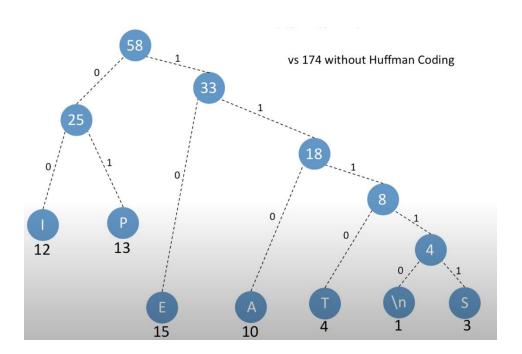
Entropy Coding

- Huffman coding
 - Based on the lengths of assigned codes on the frequency of data (prefix codes)

Character	Code	Frequency	Total Bits
Α	000 Length = 3	10	30 Frequency x Bit Length
E	001	15	45
1	010	12	36
S	011	3	12
Т	100	4	12
Р	101	13	39
Newline	110	1	3
Total Bits Used: 174			its Used: 174

Entropy coding

Huffman coding



Total Bits: 146

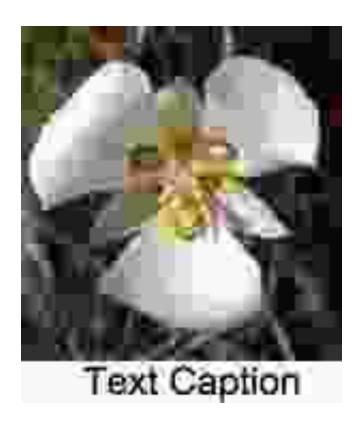
Char	Code	Freq	Total Bits
Α	110	10	30
Е	10	15	30
1	00	12	24
S	11111	3	15
Т	1110	4	16
Р	01	13	26
\n	11110	1	5

Compression Artifacts

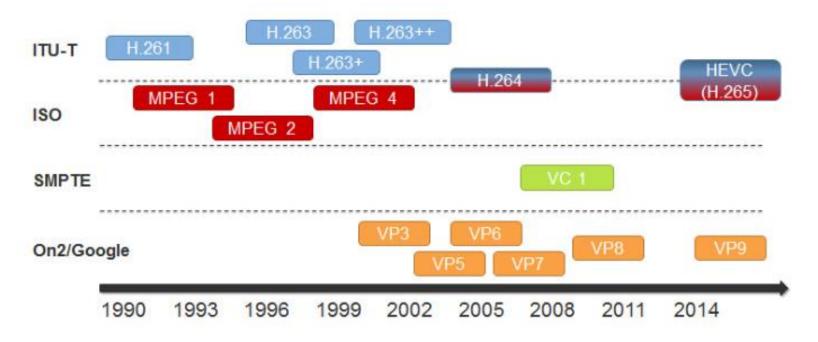
• 8x8 Blocks



Text Caption



Video Compression History



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Popular Video Compression Algorithms

- MPEG Standards
 - MPEG H.26x series, H.266 is the most recent one
 - VP series from Google
 - AV1

Lecture Summary

- 3D Live Capture
- Need for Compression
- 2D Compression key steps
 - Chroma sub-sampling
 - Frame prediction
 - Transform coding
 - Entropy coding