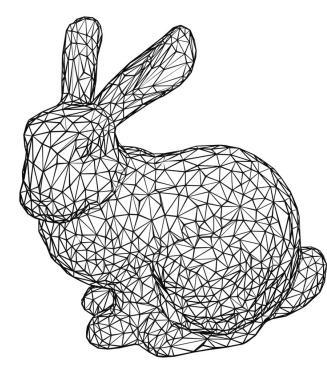
EECE5698 Networked XR Systems

Lecture Outline for Today

Recap: Mesh

- A set of polygons, connected by their common edges or vertices
- Typically represented by triangles
- Meshes are fundamental to rendering scenes in video games, animations, XR, and more.



Recap: Mesh

- Data representation
 - Each frame has vertices and connectivity
 - Color texture is stored independently, so there is also mapping information from texture to polygons

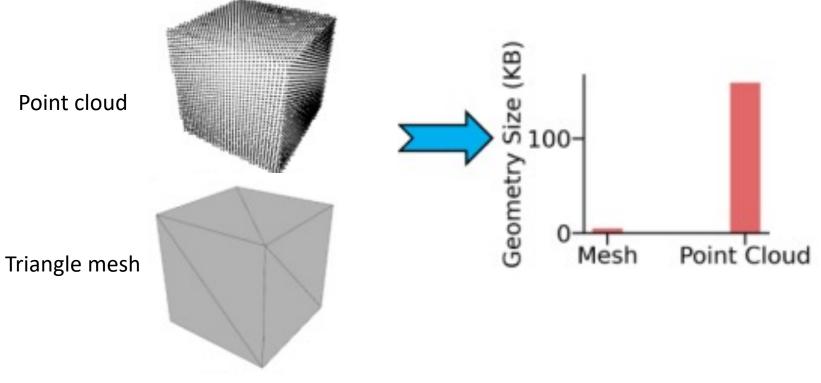


Why Mesh Compression

- **Challenges**: Large meshes consume significant memory and bandwidth, making storage and transmission inefficient.
- **Objectives**: Compress meshes to reduce file size without significantly losing quality, enabling faster loading times and lower storage requirements.
- **Benefits**: Efficient mesh compression improves performance in real-time applications and reduces costs in data transmission and storage.

Mesh vs. Point Cloud

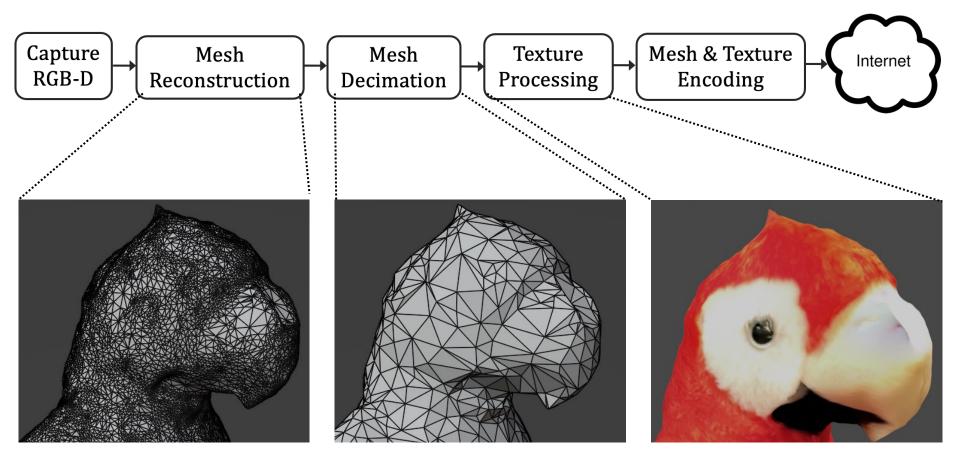
Meshes are much more compact



Counter Intuitive from the previous slide?

- Mesh Simplification Vertex clustering or quadratic error decimation
- Vertex Compression
- Connectivity Compression
- Texture Compression

Mesh simplification can be a form of compression

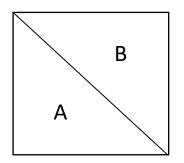


- Vertex Compression
 - Reduce the size of vertex coordinates while preserving the mesh's geometric detail.
- Techniques
 - Quantization: Converts floating-point coordinates to a fixed number of bits, reducing precision but saving space.
 - **Predictive Coding**: Encodes vertex positions as differences from predicted positions based on previous vertices, exploiting spatial coherence.
- Example: Using delta encoding, where each vertex position is stored as the difference from the previous vertex, significantly reducing the range of values.

- Vertex Compression
 - Reduce the size of vertex coordinates while preserving the mesh's geometric detail.
- Techniques:
 - Vertices can be considered same as point cloud
 - Can we use point cloud compression techniques that we discussed in the previous lecture?

- Connectivity Compression
 - Efficiently encoding the mesh topology, which defines how vertices are connected to form faces.
- Techniques Edgebreaker algorithm
 - The algorithm traverses the mesh, encoding its topology with a sequence of symbols representing the traversal operations.
 - Includes symbols like C (connect), L (left), R (right), E (end), and S (start), which describe how to move from one triangle to the next – CLERS String

- Edgebreaker Algorithm
 - The algorithm starts at an edge of the mesh and follows the edges around the mesh in a systematic way, essentially "breaking" the edges as it goes to avoid retracing its path. This traversal forms a loop around the mesh, visiting each triangle once.



Step 1: Start at the outer edge of **A** (S could denote this start, but it's optional).

Step 2: Move to triangle **B** via the shared edge — since **B** is directly connected without requiring a turn, this move is encoded as "C" (Connect).

Step 3: From **B**, there's no new triangle to visit, so the algorithm would end — this could be marked with "E" for End, but since it's a simple case, the end might be implicit.

- Connectivity Compression
 - Efficiently encoding the mesh topology, which defines how vertices are connected to form faces.
- Techniques Edgebreaker algorithm
 - Achieves at most 4 bits per vertex
 - Published in 1996 but popular even today
 - Used in Google's Draco Mesh compression code (<u>https://google.github.io/draco</u>)

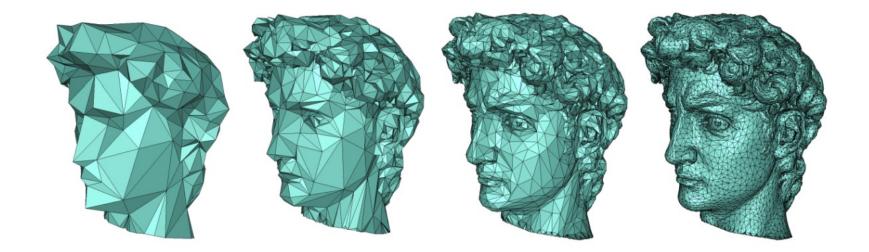
- Connectivity Compression
 - Efficiently encoding the mesh topology, which defines how vertices are connected to form faces.
- Techniques Edgebreaker algorithm
 - Limitations: the algorithm assumes a manifold mesh, which may limit its applicability to meshes with more complex topologies without preprocessing

Definition of manifold mesh: if you were a tiny ant walking on the surface of the 3D model, you could walk all over the model without ever finding a place where the surface doesn't make sense — no holes, no edges hanging in the air, and no overlapping faces.

- Connectivity Compression
 - Efficiently encoding the mesh topology, which defines how vertices are connected to form faces.
- Techniques
 - Edgebreaker lossy for non-manifold meshes
 - TFAN (Triangle fan) algorithm lossless
 - Valence-driven encoding based on the number of connected edges

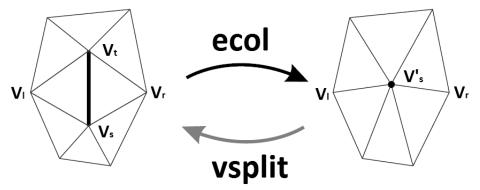
- Texture compression
 - How?

- Progressive compression
 - Different levels of detail are created by simplifying the original mesh step by step, usually by vertex decimation or edge collapse techniques.



Progressive compression

- 1. Edge Collapse: In the simplification process, an operation called "edge collapse" is frequently used, where an edge between two vertices is collapsed into a single vertex, reducing the overall count of vertices and faces.
- **2. Vertex Split**: The reverse of edge collapse is "vertex split." To refine the mesh, the algorithm splits a vertex into two and recreates the original edge and associated faces. The vertex split operation is stored as a record of how to refine the mesh from one LOD to the next.

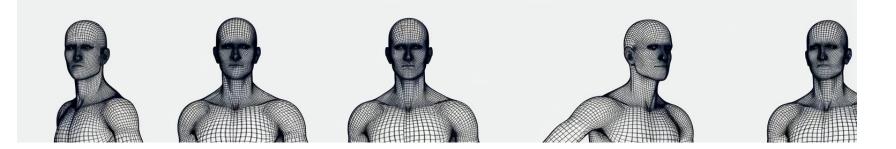


- So far, we talked about only static meshes... What about dynamic meshes?
- Animated meshes
- Sequence of mesh frames

Animated Mesh Compression

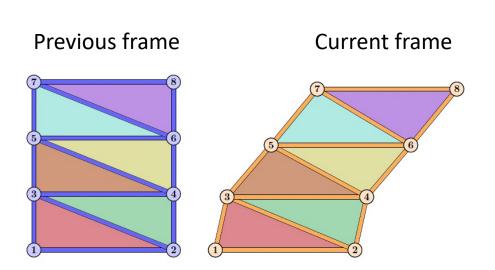
- **Sparse Keyframes**: Instead of storing every frame of the animation, only keyframes are stored, and intermediate frames are interpolated. This greatly reduces the amount of data required.
- Interpolation: The in-between frames are generated by interpolating the transformations (such as position, rotation, and scaling) from keyframes. Efficient algorithms ensure that this interpolation does not require too much computational power.

- Recall intra and inter frame prediction for exploiting spatial and temporal redundancy in 2D videos
 - Can we apply similar principles?



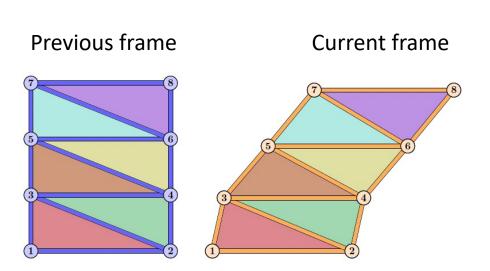
ChatGPT produced example mesh sequence

- Compress displacements instead of vertices
 - Displacements are much smaller values and require fewer bits compared to vertices



 Key assumption: vertex correspondence

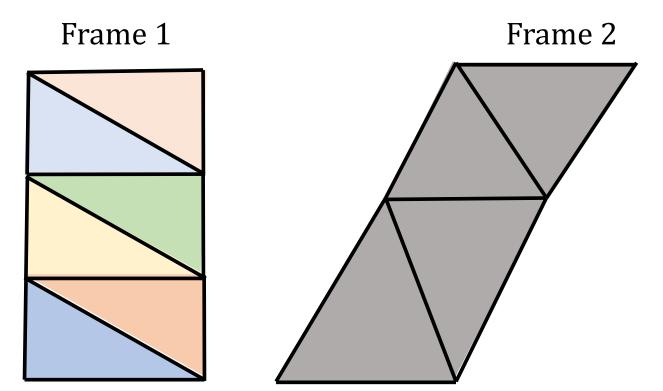
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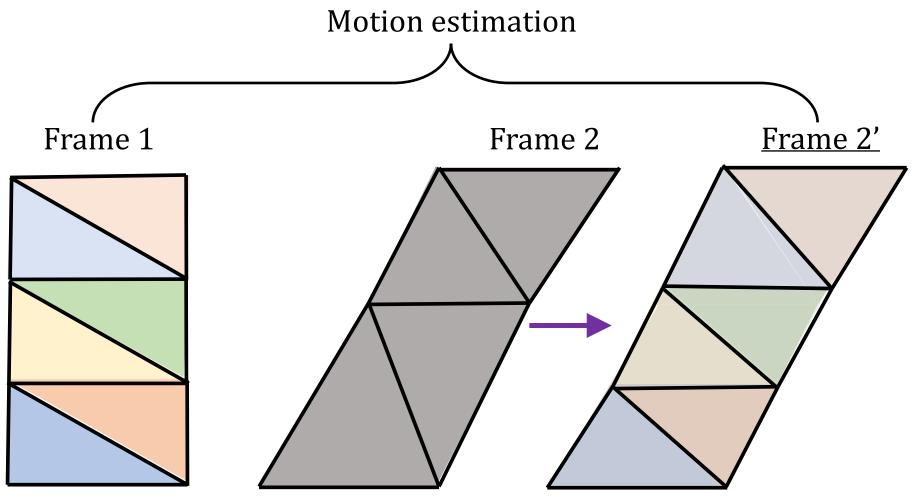


 Key assumption: vertex correspondence

Final Step: Entropy Coding

 Topology changes in practice (also called as time varying mesh)





Topology matching with subdivision

- Extract key points from each mesh
- Establish correspondences
- Apply non-rigid transformation



Open3D

- Challenges
 - Not easy to get a useful reference mesh always due to self contact or addition or deletion of geometry across time

 Still an active area of research – no open source or very well adopted techniques yet

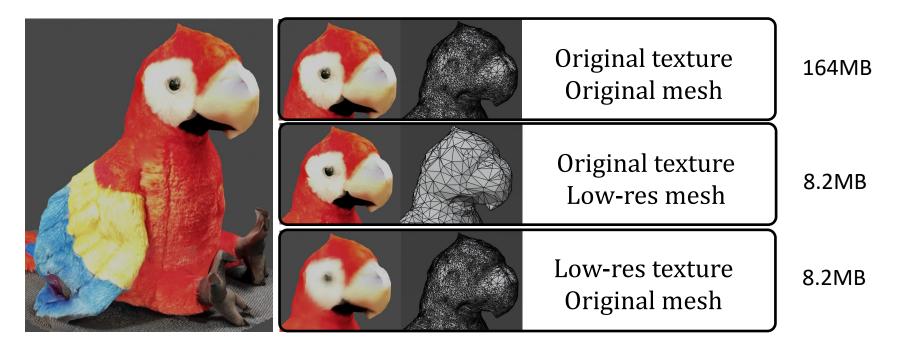
- Small-scale vs. Large scale mesh sequences
- Large meshes often tend to be static most of the regions
 - Divide the mesh into patches
 - Check if the patch is static, if so, don't store, just store a motion vector (note even in static cases topology can change but since we "know" it's a static region it's okay use the lossy reference)
 - If not static, need to store
 - Question: how to detect if it's static or moving?

Compressing mesh and texture together

- We care about the final rendered image quality so we need to optimize a function that compresses both mesh texture and mesh together
 - Need to effectively allocate bits for mesh and texture

Compressing mesh and texture together

- We care about the final rendered image quality so we need to optimize a function that compresses both mesh texture and mesh together
 - Need to effectively allocate bits for mesh and texture



- This lecture has focused mainly on compression efficiency
 - Almost all of the algorithms are computationally very expensive
 - None of the dynamic or time varying methods can run in real-time – so only suitable for offline stored applications

Summary of the Lecture

- Mesh compression
 - Vertex, connectivity, texture compression
 - Static
 - Dynamic or time varying
 - Progressive